

# Integer Set Coalescing for Polyhedral Compilation

Sven Verdoolaege

INRIA and KU Leuven

October 21, 2014

# Outline

## 1 Introduction and Motivation

- Polyhedral Compilation
- The need for coalescing
- Traditional “Coalescing”

## 2 Coalescing in `isl`

- Rational Cases
- Constraints adjacent to inequality
- Constraints adjacent to equality
- Wrapping
- Existentially Quantified Variables

## 3 Conclusions

# Outline

## 1 Introduction and Motivation

- Polyhedral Compilation
- The need for coalescing
- Traditional “Coalescing”

## 2 Coalescing in *isl*

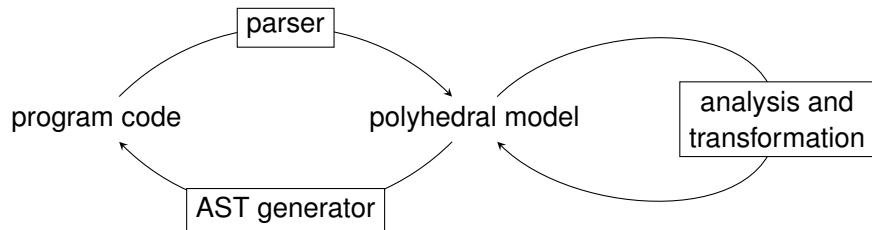
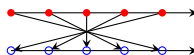
- Rational Cases
- Constraints adjacent to inequality
- Constraints adjacent to equality
- Wrapping
- Existentially Quantified Variables

## 3 Conclusions

# Polyhedral Compilation

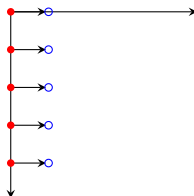
```

for (i = 0; i <= N; ++i)
  a[i] = ...
for (i = 0; i <= N; ++i)
  b[i] = f(a[N-i])
  
```



```

for (i = 0; i <= N; ++i) {
  a[i] = ...
  b[N-i] = f(a[i])
}
  
```



# Polyhedral Model

```
R:  h(A[2]);  
    for (int i = 0; i < 2; ++i)  
        for (int j = 0; j < 2; ++j)  
S:      A[i + j] = f(i, j);  
    for (int k = 0; k < 2; ++k)  
T:      g(A[k], A[0]);
```

## Polyhedral Model

```
R:  h(A[2]);  
    for (int i = 0; i < 2; ++i)  
        for (int j = 0; j < 2; ++j)  
S:      A[i + j] = f(i, j);  
    for (int k = 0; k < 2; ++k)  
T:      g(A[k], A[0]);
```

- instance based

- Instance set (set of statement instances)

$$I = \{R(); S(0,0); S(0,1); S(1,0); S(1,1); T(0); T(1)\}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
        for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based

- Instance set (set of statement instances)

$$I = \{ R(); S(0,0); S(0,1); S(1,0); S(1,1); T(0); T(1) \}$$

- Access relations (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(0,0) \rightarrow A(0); S(0,1) \rightarrow A(1); S(1,0) \rightarrow A(1); \\ S(1,1) \rightarrow A(2) \}$$

$$R = \{ R() \rightarrow A(2); T(0) \rightarrow A(0); T(1) \rightarrow A(1); T(1) \rightarrow A(0) \}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);

```

- instance based

- Instance set (set of statement instances)

$$I = \{ R(); S(0,0); S(0,1); S(1,0); S(1,1); T(0); T(1) \}$$

- Access relations (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(0,0) \rightarrow A(0); S(0,1) \rightarrow A(1); S(1,0) \rightarrow A(1); \\ S(1,1) \rightarrow A(2) \}$$

$$R = \{ R() \rightarrow A(2); T(0) \rightarrow A(0); T(1) \rightarrow A(1); T(1) \rightarrow A(0) \}$$

- Schedule (execution order)

$$\{ R() \rightarrow (0); S(0,0) \rightarrow (1); S(0,1) \rightarrow (2); S(1,0) \rightarrow (3); \\ S(1,1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$



# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based
- compact representation

- Instance set (set of statement instances)

$$I = \{R(); S(0,0); S(0,1); S(1,0); S(1,1); T(0); T(1)\}$$

- Access relation (accesses array elements that will be read)

$$W = \{S(0,0) \rightarrow A(0); S(0,1) \rightarrow A(1); S(1,0) \rightarrow A(1); S(1,1) \rightarrow A(2)\}$$

$$R = \{R() \rightarrow A(2); T(0) \rightarrow A(0); T(1) \rightarrow A(1); T(1) \rightarrow A(0)\}$$

- Schedule (execution order)

$$\{R() \rightarrow (0); S(0,0) \rightarrow (1); S(0,1) \rightarrow (2); S(1,0) \rightarrow (3); S(1,1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6)\}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:  A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:  g(A[k], A[0]);
  
```

- instance based
- compact representation

- Instance set (set of statement instances)

$$I = \{ R(); S(0,0); S(0,1); S(1,0); S(1,1); T(0); T(1) \}$$

- Access relation  $\{ R(); S(i,j) : 0 \leq i < 2 \wedge 0 \leq j < 2; T(k) : 0 \leq k < 2; \}$

$$W = \{ S(0,0) \rightarrow A(0); S(0,1) \rightarrow A(1); S(1,0) \rightarrow A(1);$$

$$S(1,1) \rightarrow A(0);$$

$$R = \{ R(); S(0,0) \rightarrow A(0); S(0,1) \rightarrow A(1); S(1,0) \rightarrow A(1); S(1,1) \rightarrow A(0); T(0) \rightarrow A(0); T(1) \rightarrow A(0) \}$$

- Schedule (execution order)

$$\{ R() \rightarrow (0); S(0,0) \rightarrow (1); S(0,1) \rightarrow (2); S(1,0) \rightarrow (3);$$

$$S(1,1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based
- compact representation

- **Instance set** (set of statement instances)

$$I = \{ R(); S(i, j) : 0 \leq i < 2 \wedge 0 \leq j < 2; T(k) : 0 \leq k < 2 \}$$

- **Access relations** (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(0, 0) \rightarrow A(0); S(0, 1) \rightarrow A(1); S(1, 0) \rightarrow A(1); \\ S(1, 1) \rightarrow A(2) \}$$

$$R = \{ R() \rightarrow A(2); T(0) \rightarrow A(0); T(1) \rightarrow A(1); T(1) \rightarrow A(0) \}$$

- **Schedule** (execution order)

$$\{ R() \rightarrow (0); S(0, 0) \rightarrow (1); S(0, 1) \rightarrow (2); S(1, 0) \rightarrow (3); \\ S(1, 1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based
- compact representation

- **Instance set** (set of statement instances)

$$I = \{ R(); S(i, j) : 0 \leq i < 2 \wedge 0 \leq j < 2; T(k) : 0 \leq k < 2 \}$$

- **Access relations** (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(0, 0) \rightarrow A(0); S(0, 1) \rightarrow A(1); S(1, 0) \rightarrow A(1); S(1, 1) \rightarrow A(2) \}$$

$$R = \{ R(); \{ S(i, j) \rightarrow A(i + j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \} \rightarrow A(0) \}$$

- **Schedule** (execution order)

$$\{ R() \rightarrow (0); S(0, 0) \rightarrow (1); S(0, 1) \rightarrow (2); S(1, 0) \rightarrow (3); S(1, 1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based
- compact representation

- **Instance set** (set of statement instances)

$$I = \{ R(); S(i, j) : 0 \leq i < 2 \wedge 0 \leq j < 2; T(k) : 0 \leq k < 2 \}$$

- **Access relations** (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(i, j) \rightarrow A(i + j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \}$$

$$R = \{ R() \rightarrow A(2); T(0) \rightarrow A(0); T(1) \rightarrow A(1); T(1) \rightarrow A(0) \}$$

- **Schedule** (execution order)

$$\{ R() \rightarrow (0); S(0, 0) \rightarrow (1); S(0, 1) \rightarrow (2); S(1, 0) \rightarrow (3); \\ S(1, 1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based
- compact representation

- Instance set (set of statement instances)

$$I = \{ R(); S(i, j) : 0 \leq i < 2 \wedge 0 \leq j < 2; T(k) : 0 \leq k < 2 \}$$

- Access relations (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(i, j) \rightarrow A(i + j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \}$$

$$R = \{ R() \rightarrow A(2); T(0) \rightarrow A(0); T(1) \rightarrow A(1); T(1) \rightarrow A(0) \}$$

- Schedule (execution order)
 
$$\{ R() \rightarrow A(2); T(k) \rightarrow A(0) : 0 \leq k < 2; T(k) \rightarrow A(k) : 0 \leq k < 2 \}$$

$$\{ R() \rightarrow (0); S(0, 0) \rightarrow (1); S(0, 1) \rightarrow (2); S(1, 0) \rightarrow (3);$$

$$S(1, 1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based
- compact representation

- **Instance set** (set of statement instances)

$$I = \{ R(); S(i, j) : 0 \leq i < 2 \wedge 0 \leq j < 2; T(k) : 0 \leq k < 2 \}$$

- **Access relations** (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(i, j) \rightarrow A(i + j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \}$$

$$R = \{ R() \rightarrow A(2); T(k) \rightarrow A(0) : 0 \leq k < 2; T(k) \rightarrow A(k) : 0 \leq k < 2 \}$$

- **Schedule** (execution order)

$$\{ R() \rightarrow (0); S(0, 0) \rightarrow (1); S(0, 1) \rightarrow (2); S(1, 0) \rightarrow (3); \\ S(1, 1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$

# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based
- compact representation

- Instance set (set of statement instances)

$$I = \{ R(); S(i, j) : 0 \leq i < 2 \wedge 0 \leq j < 2; T(k) : 0 \leq k < 2 \}$$

- Access relations (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(i, j) \rightarrow A(i + j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \}$$

$$\{ R() \rightarrow (0); S(i, j) \rightarrow (1 + 2i + j) : 0 \leq i, j < 2; T(k) \rightarrow (5 + k) : 0 \leq k < 2 \}$$

- Schedule (execution order)

$$\{ R() \rightarrow (0); S(0, 0) \rightarrow (1); S(0, 1) \rightarrow (2); S(1, 0) \rightarrow (3); S(1, 1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$



# Polyhedral Model

```

R:  h(A[2]);
    for (int i = 0; i < 2; ++i)
      for (int j = 0; j < 2; ++j)
S:      A[i + j] = f(i, j);
    for (int k = 0; k < 2; ++k)
T:      g(A[k], A[0]);
  
```

- instance based
- compact representation

- Instance set (set of statement instances)

$$I = \{ R(); S(i, j) : 0 \leq i < 2 \wedge 0 \leq j < 2; T(k) : 0 \leq k < 2 \}$$

- Access relations (accessed array elements;  $W$ : write,  $R$ : read)

$$W = \{ S(i, j) \rightarrow A(i + j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \}$$

$$\{ R() \rightarrow (0); S(i, j) \rightarrow (1 + 2i + j) : 0 \leq i, j < 2; T(k) \rightarrow (5 + k) : 0 \leq k < 2 \}$$

$$\{ R() \rightarrow (0, 0, 0); S(i, j) \rightarrow (1, i, j) : 0 \leq i, j < 2; T(k) \rightarrow (2, k, 0) : 0 \leq k < 2 \}$$

$$\{ R() \rightarrow (0); S(0, 0) \rightarrow (1); S(0, 1) \rightarrow (2); S(1, 0) \rightarrow (3); S(1, 1) \rightarrow (4); T(0) \rightarrow (5); T(1) \rightarrow (6) \}$$

# Equivalent Representations

$$\begin{aligned} \text{extensive} \quad & \{ S(0,0); S(0,1); S(1,0); S(1,1) \} \\ &= \{ S(i,j) : (i=0 \wedge j=0) \vee (i=0 \wedge j=1) \vee \\ &\quad (i=1 \wedge j=0) \vee (i=1 \wedge j=1) \} \\ \text{intensive} \quad & \{ S(i,j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \} \end{aligned}$$

# Equivalent Representations

extensive	$\{ S(0,0); S(0,1); S(1,0); S(1,1) \}$ $= \{ S(i,j) : (i = 0 \wedge j = 0) \vee (i = 0 \wedge j = 1) \vee$ $(i = 1 \wedge j = 0) \vee (i = 1 \wedge j = 1) \}$
intensive	$\{ S(i,j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \}$
alternative	$\{ S(i,j) : (i = 0 \wedge 0 \leq j < 2) \vee (i = 1 \wedge 0 \leq j < 2) \}$

# Equivalent Representations

extensive	$\{ S(0, 0); S(0, 1); S(1, 0); S(1, 1) \}$	4
	$= \{ S(i, j) : (i = 0 \wedge j = 0) \vee (i = 0 \wedge j = 1) \vee (i = 1 \wedge j = 0) \vee (i = 1 \wedge j = 1) \}$	
intensive	$\{ S(i, j) : 0 \leq i < 2 \wedge 0 \leq j < 2 \}$	1
alternative	$\{ S(i, j) : (i = 0 \wedge 0 \leq j < 2) \vee (i = 1 \wedge 0 \leq j < 2) \}$	2

In general, representation with fewer **disjuncts** is preferred

- (usually) occupies less memory
- operations can be performed more efficiently
- the outcome of some operations depends on chosen representation
  - ▶ transitive closure approximation
  - ▶ AST generation

⇒ coalescing: replace representation by one with fewer disjuncts

# Effect on AST Generation — guide

Without coalescing

```
for (int c0 = 1; c0 <= min(2 * M, N); c0 += 1)
    S1(c0);
for (int c0 = max(1, 2 * M + 1); c0 <= N; c0 += 1)
    S1(c0);
for (int c0 = N + 1; c0 <= 2 * N; c0 += 1)
    S2(c0);
```

With coalescing

```
for (int c0 = 1; c0 <= N; c0 += 1)
    S1(c0);
for (int c0 = N + 1; c0 <= 2 * N; c0 += 1)
    S2(c0);
```

## Effect on AST Generation — cholesky2

Without coalescing (fragment)

```
for (int c0 = 1; c0 < 3 * M - 1; c0 += 3) {  
    S3((c0 + 2) / 3);  
    if (3 * M >= c0 + 8) {  
        for (int c1 = (c0 + 5) / 3; c1 <= M; c1 += 1) {  
            S6((c0 + 2) / 3, c1);  
            for (int c4 = (c0 + 5) / 3; c4 < c1; c4 += 1)  
                S5(c4, c1, (c0 + 2) / 3);  
        }  
    } else if (c0 + 5 == 3 * M)  
        S6(M - 1, M);  
}
```

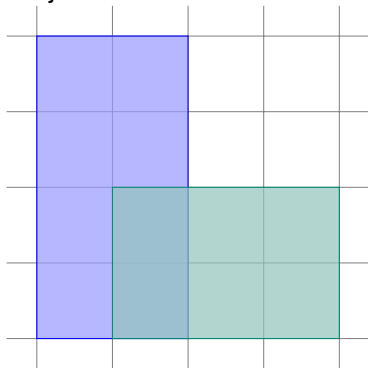
With coalescing (fragment)

```
for (int c0 = 1; c0 < 3 * M - 1; c0 += 3) {  
    S3((c0 + 2) / 3);  
    for (int c1 = (c0 + 5) / 3; c1 <= M; c1 += 1) {  
        S6((c0 + 2) / 3, c1);  
        for (int c4 = (c0 + 5) / 3; c4 < c1; c4 += 1)  
            S5(c4, c1, (c0 + 2) / 3);  
    }  
}
```

# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

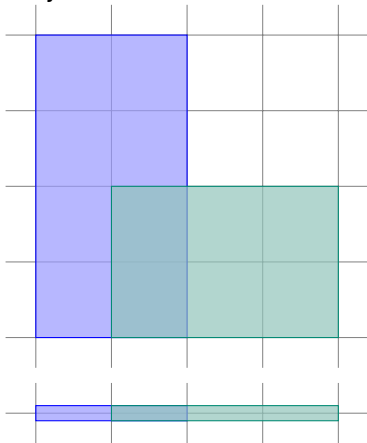
- Projection



# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection

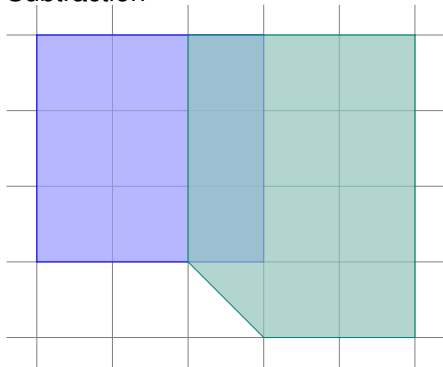




# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

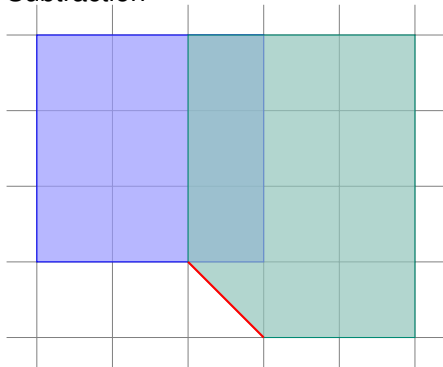
- Projection
- Subtraction



# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

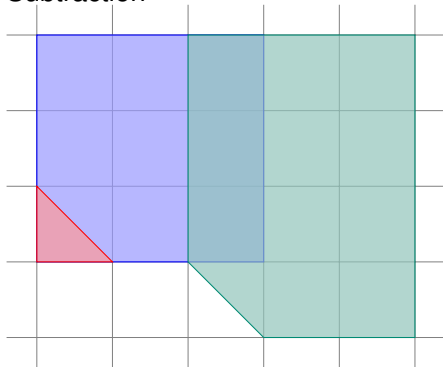
- Projection
- Subtraction



# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

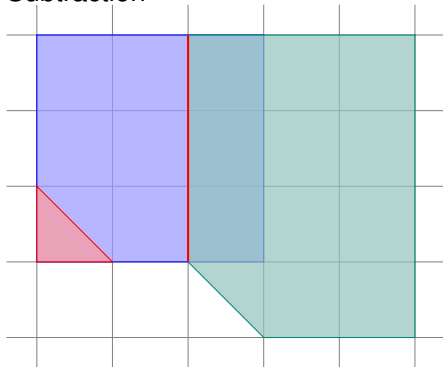
- Projection
- Subtraction



# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

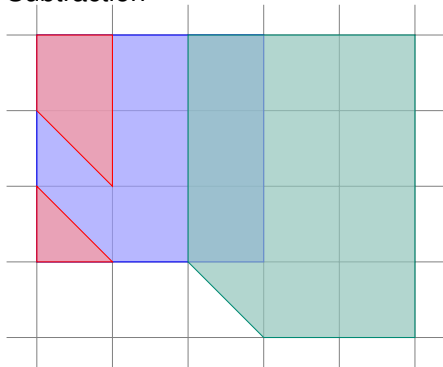
- Projection
- Subtraction



# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction



## Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

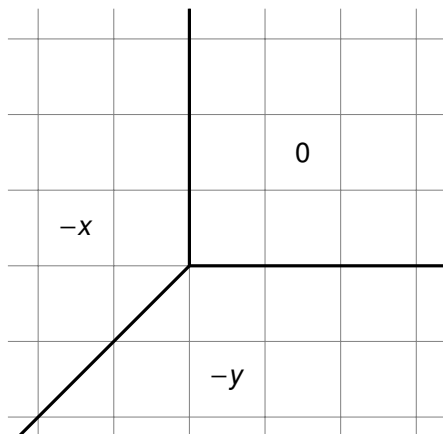
$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$

## Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$

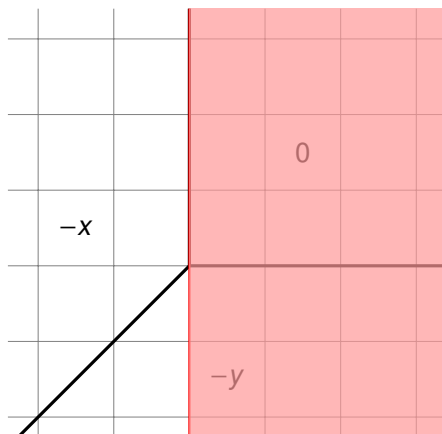


# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$



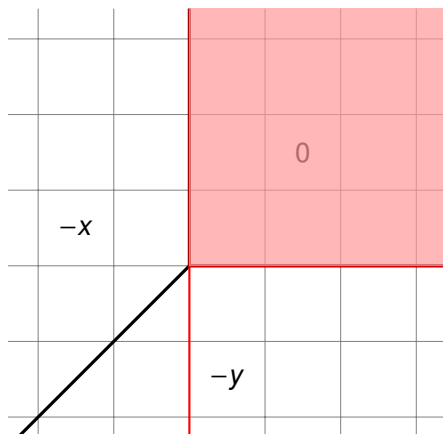


## Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$

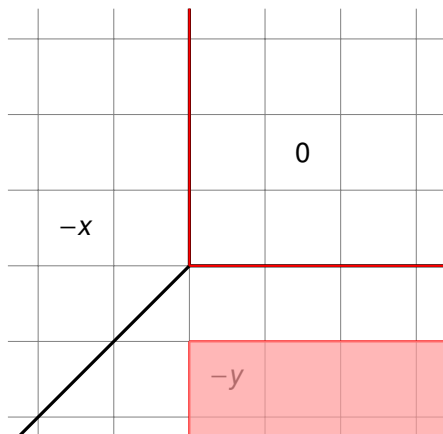


# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$

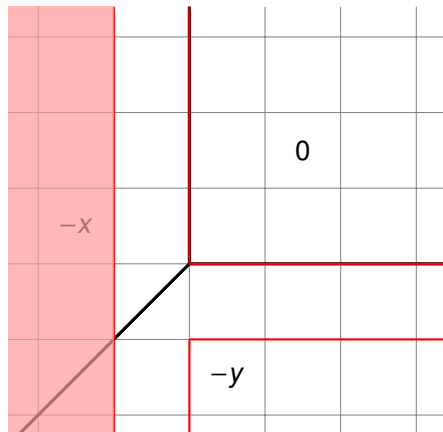


## Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$

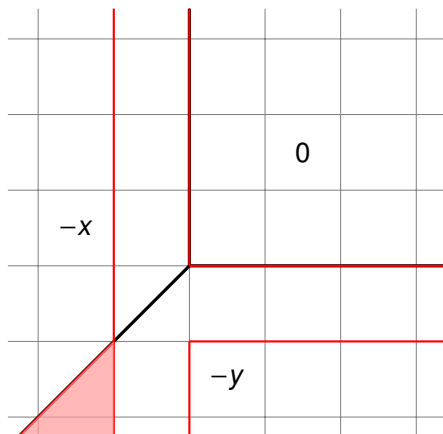


# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$

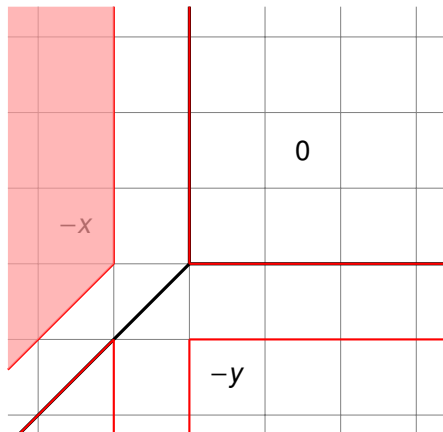


# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$

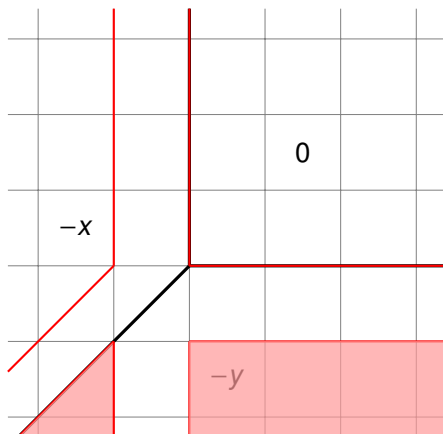


# Causes of Splintering

Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming

$$\min \{ (x, y) \rightarrow (z) : z \geq 0 \wedge x + z \geq 0 \wedge x + y \geq 0 \}$$



# Causes of Splintering

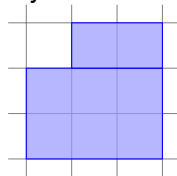
Several operations on integer sets may introduce coalescing opportunities

- Projection
- Subtraction
- Parametric integer programming
- Union

# Traditional “Coalescing”

Traditional method (e.g., in CLooG with original PolyLib backend)

- 1 Compute convex hull  $H$  of  $S$
- 2 Remove integer elements not in  $S$  from  $H$   
 $\Rightarrow H \setminus (H \setminus S)$

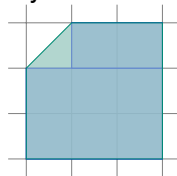




# Traditional “Coalescing”

Traditional method (e.g., in CLooG with original PolyLib backend)

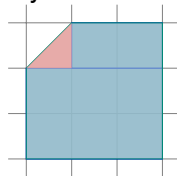
- 1 Compute convex hull  $H$  of  $S$
- 2 Remove integer elements not in  $S$  from  $H$   
 $\Rightarrow H \setminus (H \setminus S)$



# Traditional “Coalescing”

Traditional method (e.g., in CLooG with original PolyLib backend)

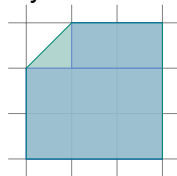
- 1 Compute convex hull  $H$  of  $S$
- 2 Remove integer elements not in  $S$  from  $H$   
 $\Rightarrow H \setminus (H \setminus S)$



# Traditional “Coalescing”

Traditional method (e.g., in CLooG with original PolyLib backend)

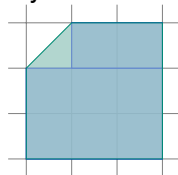
- 1 Compute convex hull  $H$  of  $S$
- 2 Remove **integer** elements not in  $S$  from  $H$   
 $\Rightarrow H \setminus (H \setminus S)$



## Traditional “Coalescing”

Traditional method (e.g., in CLoog with original PolyLib backend)

- 1 Compute convex hull  $H$  of  $S$
- 2 Remove integer elements not in  $S$  from  $H$   
 $\Rightarrow H \setminus (H \setminus S)$



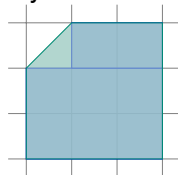
Issues:

- Convex hull may have exponential number of constraints  
We may be able to remove some of them, but we still need to compute them first.
- Constraints of convex hull may have very large coefficients
- Convex hull is an operation on *rational* sets
  - $\Rightarrow$  mixture of operation on rational sets (convex hull) and integer sets (set subtraction)
  - $\Rightarrow$  in isl, convex hull operation not fully defined on sets with existentially quantified variables
- Convex hull is costly to compute

## Traditional “Coalescing”

Traditional method (e.g., in CLoog with original PolyLib backend)

- 1 Compute convex hull  $H$  of  $S$
- 2 Remove integer elements not in  $S$  from  $H$   
 $\Rightarrow H \setminus (H \setminus S)$



Issues:

- Convex hull may have exponential number of constraints  
We may be able to remove some of them, but we still need to compute them first.
- Constraints of convex hull may have very large coefficients
- Convex hull is an operation on *rational* sets
  - $\Rightarrow$  mixture of operation on rational sets (convex hull) and integer sets (set subtraction)
  - $\Rightarrow$  in isl, convex hull operation not fully defined on sets with existentially quantified variables
- Convex hull is costly to compute

## Effect on AST Generation — covariance

With `isl` coalescing (in this case same result as no coalescing)

```
for (long c1 = n >= 1 ? ((n - 1) % 32) - n - 31 : 0;  
      c1 <= (n >= 1 ? n - 1 : 0); c1 += 32) {  
    /* .. */  
}
```

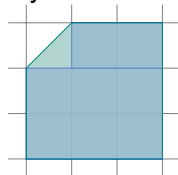
With convex hull based “coalescing”

```
for (long c1 = 32 * floord(-1073741839 * n -  
                          32749125633, 68719476720) - 1073741792; c1 <=  
      floord(715827882 * n + 357913941, 1431655765) +  
      1073741823; c1 += 32) {  
    /* .. */  
}
```

## Traditional “Coalescing”

Traditional method (e.g., in CLoog with original PolyLib backend)

- 1 Compute convex hull  $H$  of  $S$
- 2 Remove integer elements not in  $S$  from  $H$   
 $\Rightarrow H \setminus (H \setminus S)$



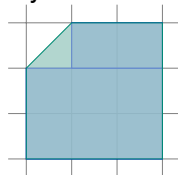
Issues:

- Convex hull may have exponential number of constraints  
We may be able to remove some of them, but we still need to compute them first.
- Constraints of convex hull may have very large coefficients
- Convex hull is an operation on *rational* sets
  - $\Rightarrow$  mixture of operation on rational sets (convex hull) and integer sets (set subtraction)
  - $\Rightarrow$  in isl, convex hull operation not fully defined on sets with existentially quantified variables
- Convex hull is costly to compute

## Traditional “Coalescing”

Traditional method (e.g., in CLoog with original PolyLib backend)

- 1 Compute convex hull  $H$  of  $S$
- 2 Remove integer elements not in  $S$  from  $H$   
 $\Rightarrow H \setminus (H \setminus S)$



Issues:

- Convex hull may have exponential number of constraints  
We may be able to remove some of them, but we still need to compute them first.
- Constraints of convex hull may have very large coefficients
- Convex hull is an operation on *rational* sets
  - $\Rightarrow$  mixture of operation on rational sets (convex hull) and integer sets (set subtraction)
  - $\Rightarrow$  in isl, convex hull operation not fully defined on sets with existentially quantified variables
- **Convex hull is costly to compute**



# AST Generation Times

Generation times on `isl` AST generation test cases

<code>isl</code> coalescing	16.0s
no coalescing	16.3s
convex hull (FM)	24m00s
convex hull (wrapping)	6m40s

Note: `isl` may not have the most efficient convex hull implementation  
However, double description based implementations are costly too

# Outline

## 1 Introduction and Motivation

- Polyhedral Compilation
- The need for coalescing
- Traditional “Coalescing”

## 2 Coalescing in isl

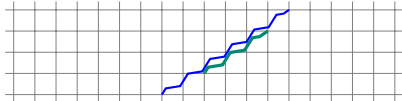
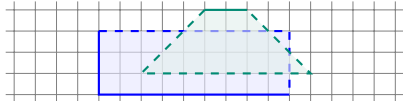
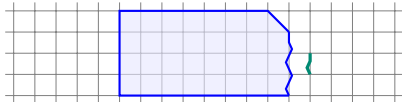
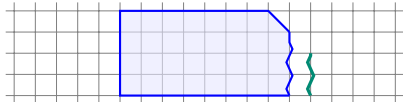
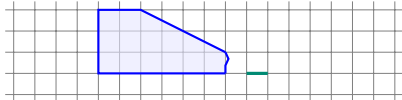
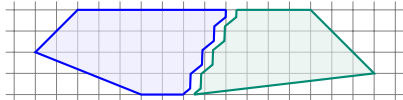
- Rational Cases
- Constraints adjacent to inequality
- Constraints adjacent to equality
- Wrapping
- Existentially Quantified Variables

## 3 Conclusions

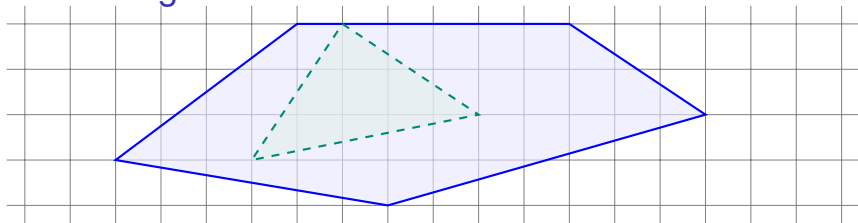
# Coalescing in isl

## Coalescing in isl

- never increases the total number of constraints
- based on solving LP problems with same dimension as input set
- recognizes a set of patterns



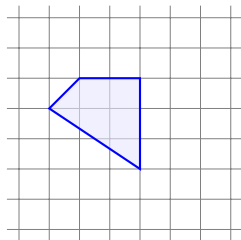
# Coalescing Cases



## Constraint types

Given two disjuncts  $A$  and  $B$

For each affine constraint  $t(\mathbf{x}) \geq 0$  of  $A$ , determine its effect on  $B$



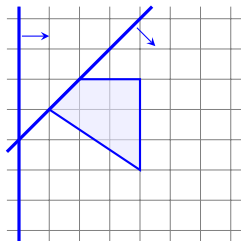
Note: affine expression  $t(\mathbf{x}) \geq 0$  has integer coefficients  
min and max computed using (incremental) LP solver

# Constraint types

Given two disjuncts  $A$  and  $B$

For each affine constraint  $t(\mathbf{x}) \geq 0$  of  $A$ , determine its effect on  $B$

- $\min t(\mathbf{x}) > -1$  over  $B$   
 $\Rightarrow$  valid constraint



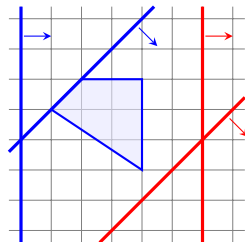
Note: affine expression  $t(\mathbf{x}) \geq 0$  has integer coefficients  
min and max computed using (incremental) LP solver

# Constraint types

Given two disjuncts  $A$  and  $B$

For each affine constraint  $t(\mathbf{x}) \geq 0$  of  $A$ , determine its effect on  $B$

- $\min t(\mathbf{x}) > -1$  over  $B$   
 $\Rightarrow$  **valid** constraint
- $\max t(\mathbf{x}) < 0$  over  $B$   
 $\Rightarrow$  **separating** constraint



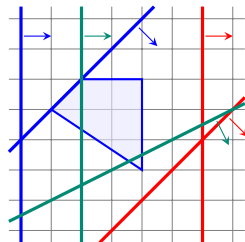
Note: affine expression  $t(\mathbf{x}) \geq 0$  has integer coefficients  
min and max computed using (incremental) LP solver

# Constraint types

Given two disjuncts  $A$  and  $B$

For each affine constraint  $t(\mathbf{x}) \geq 0$  of  $A$ , determine its effect on  $B$

- $\min t(\mathbf{x}) > -1$  over  $B$   
 $\Rightarrow$  **valid** constraint
- $\max t(\mathbf{x}) < 0$  over  $B$   
 $\Rightarrow$  **separating** constraint

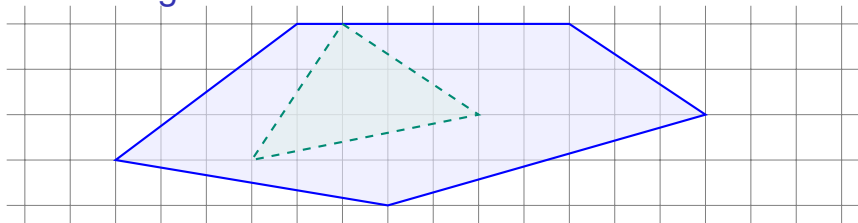


- otherwise (attains both positive and negative values over  $B$ )  
 $\Rightarrow$  **cut** constraint

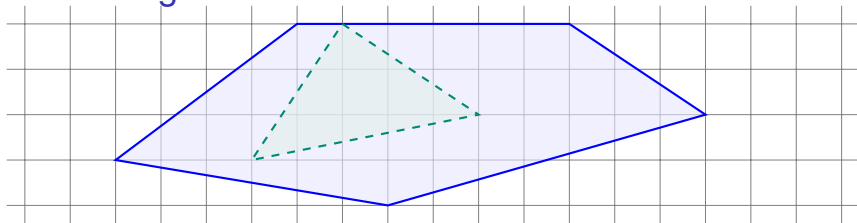
Note: affine expression  $t(\mathbf{x}) \geq 0$  has integer coefficients  
min and max computed using (incremental) LP solver



# Coalescing Cases



# Coalescing Cases

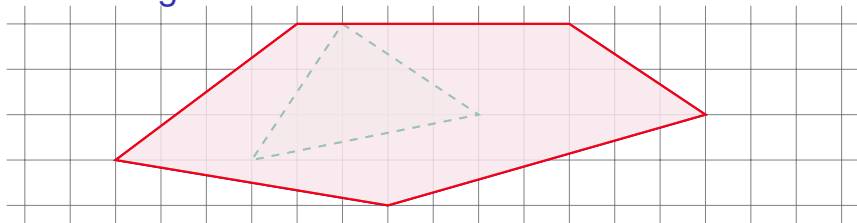


- 1 All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases

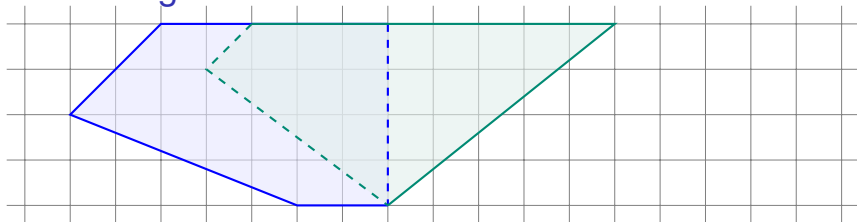


- ① All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases

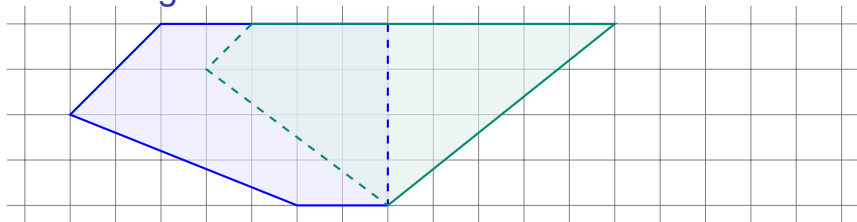


- ① All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases

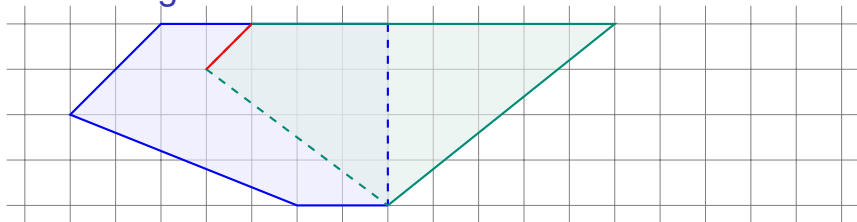


- 1 All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$
- 2 Neither  $A$  nor  $B$  have separating constraints and all cut constraints of  $A$  are valid for the cut facets of  $B$   
 $\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases

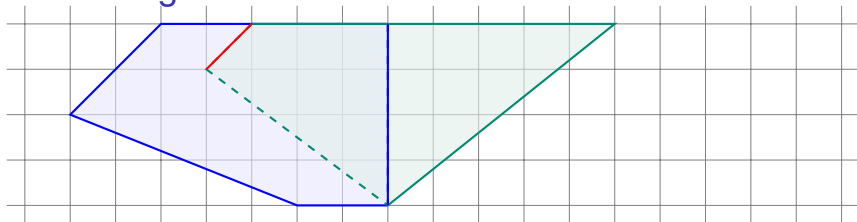


- 1 All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$
- 2 Neither  $A$  nor  $B$  have separating constraints and all cut constraints of  $A$  are valid for the cut facets of  $B$   
 $\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases

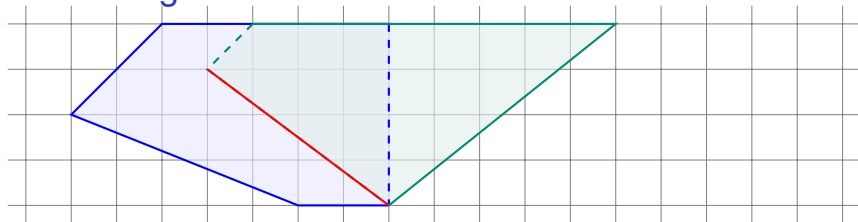


- 1 All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$
- 2 Neither  $A$  nor  $B$  have separating constraints and all cut constraints of  $A$  are valid for the cut facets of  $B$   
 $\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases



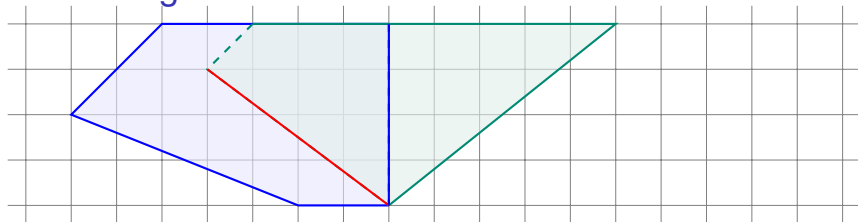
- 1 All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$
- 2 Neither  $A$  nor  $B$  have separating constraints and all cut constraints of  $A$  are valid for the cut facets of  $B$   
 $\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise



# Coalescing Cases

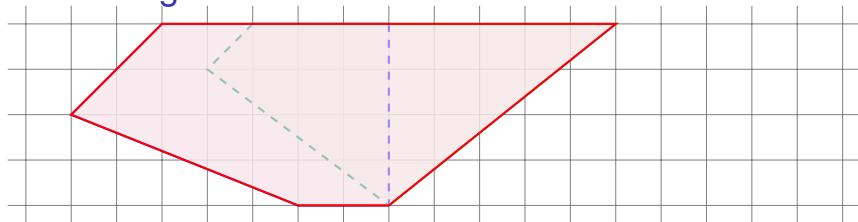


- 1 All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$
- 2 Neither  $A$  nor  $B$  have separating constraints and all cut constraints of  $A$  are valid for the cut facets of  $B$   
 $\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases

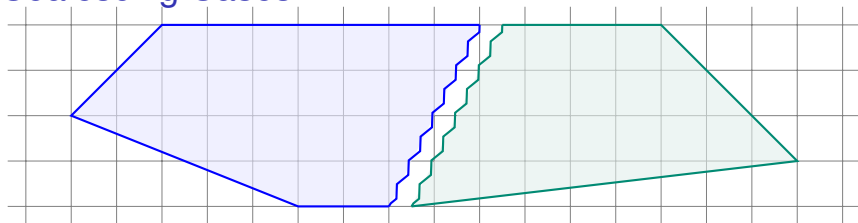


- 1 All constraints of  $A$  are valid for  $B$   
 $\Rightarrow$  drop  $B$
- 2 Neither  $A$  nor  $B$  have separating constraints and all cut constraints of  $A$  are valid for the cut facets of  $B$   
 $\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases



Constraint  $t(\mathbf{x}) \geq 0$

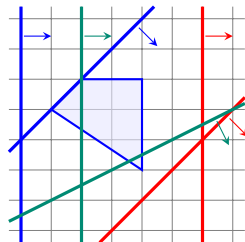
- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Constraint types

Given two disjuncts  $A$  and  $B$

For each affine constraint  $t(\mathbf{x}) \geq 0$  of  $A$ , determine its effect on  $B$

- $\min t(\mathbf{x}) > -1$  over  $B$   
 $\Rightarrow$  **valid** constraint
- $\max t(\mathbf{x}) < 0$  over  $B$   
 $\Rightarrow$  **separating** constraint



- otherwise (attains both positive and negative values over  $B$ )  
 $\Rightarrow$  **cut** constraint

Note: affine expression  $t(\mathbf{x}) \geq 0$  has integer coefficients  
min and max computed using (incremental) LP solver

# Constraint types

Given two disjuncts  $A$  and  $B$

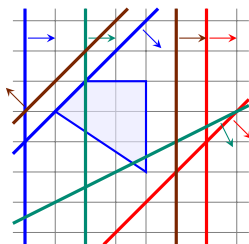
For each affine constraint  $t(\mathbf{x}) \geq 0$  of  $A$ , determine its effect on  $B$

- $\min t(\mathbf{x}) > -1$  over  $B$   
 $\Rightarrow$  **valid** constraint
- $\max t(\mathbf{x}) < 0$  over  $B$   
 $\Rightarrow$  **separating** constraint

special cases:

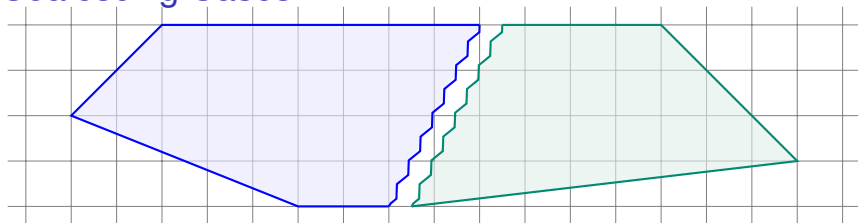
- $t = -u - 1$  with  $u(\mathbf{x}) \geq 0$  a constraints of  $B$   
 $\Rightarrow$  constraint is **adjacent to an inequality** of  $B$

- otherwise (attains both positive and negative values over  $B$ )  
 $\Rightarrow$  **cut** constraint



Note: affine expression  $t(\mathbf{x}) \geq 0$  has integer coefficients  
 min and max computed using (incremental) LP solver

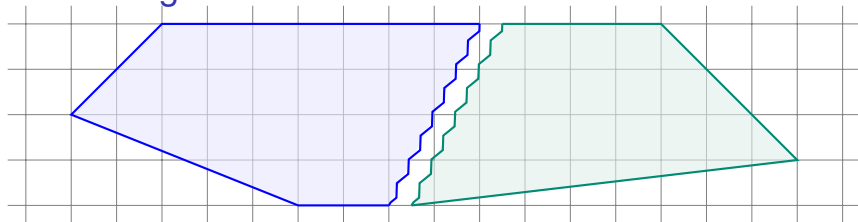
# Coalescing Cases



Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$
- cut: otherwise

# Coalescing Cases



- ③ single pair of adjacent inequalities  
(other constraints valid)

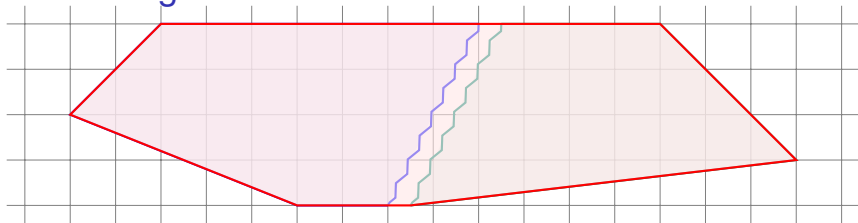
⇒ replace  $A \cup B$  by set bounded by  
all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$

- cut: otherwise

# Coalescing Cases



- ③ single pair of adjacent inequalities  
(other constraints valid)

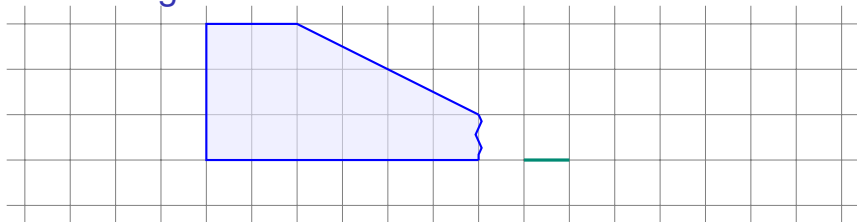
⇒ replace  $A \cup B$  by set bounded by  
all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
- cut: otherwise



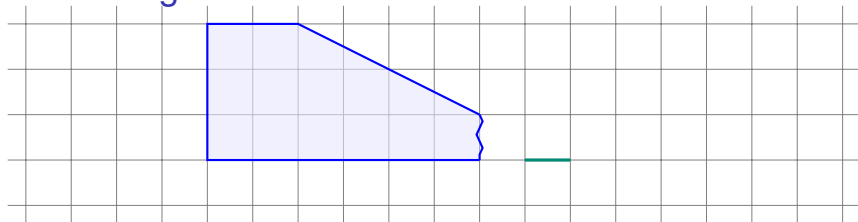
# Coalescing Cases



Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
- cut: otherwise

# Coalescing Cases

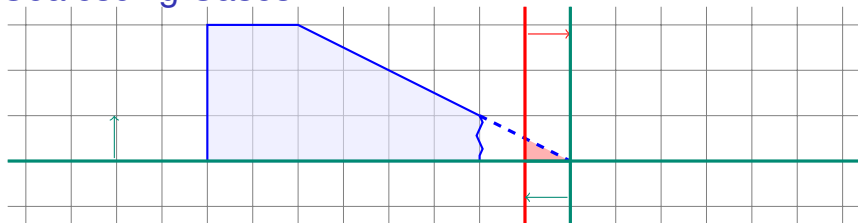


- ④  $A$  has single inequality adjacent to inequality of  $B$  (other constraints of  $A$  are valid)

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
- cut: otherwise

# Coalescing Cases



- ④  $A$  has single inequality adjacent to inequality of  $B$  (other constraints of  $A$  are valid)

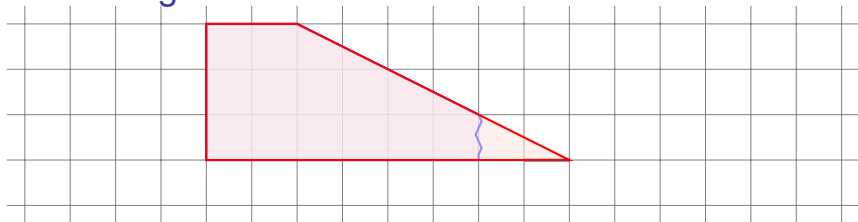
Result of replacing  $t(\mathbf{x}) \geq 0$  by  $t(\mathbf{x}) \leq -1$  and adding valid constraints of  $B$  is a subset of  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  
 $t = -u - 1$
- cut: otherwise

# Coalescing Cases



- ④  $A$  has single inequality adjacent to inequality of  $B$  (other constraints of  $A$  are valid)

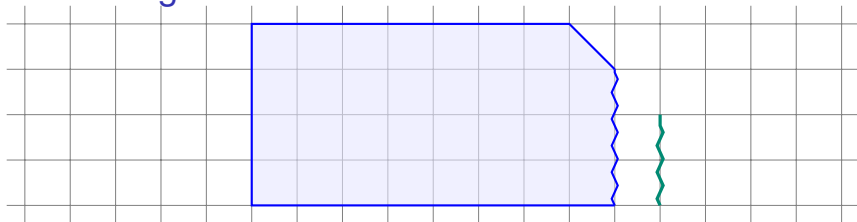
Result of replacing  $t(\mathbf{x}) \geq 0$  by  $t(\mathbf{x}) \leq -1$  and adding valid constraints of  $B$  is a subset of  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  
 $t = -u - 1$
- cut: otherwise

# Coalescing Cases



Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
- cut: otherwise

# Constraint types

Given two disjuncts  $A$  and  $B$

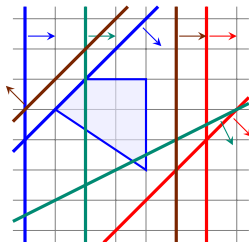
For each affine constraint  $t(\mathbf{x}) \geq 0$  of  $A$ , determine its effect on  $B$

- $\min t(\mathbf{x}) > -1$  over  $B$   
 $\Rightarrow$  **valid** constraint
- $\max t(\mathbf{x}) < 0$  over  $B$   
 $\Rightarrow$  **separating** constraint

special cases:

- $t = -u - 1$  with  $u(\mathbf{x}) \geq 0$  a constraints of  $B$   
 $\Rightarrow$  constraint is **adjacent to an inequality** of  $B$

- otherwise (attains both positive and negative values over  $B$ )  
 $\Rightarrow$  **cut** constraint



Note: affine expression  $t(\mathbf{x}) \geq 0$  has integer coefficients  
 min and max computed using (incremental) LP solver

# Constraint types

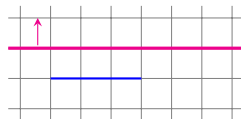
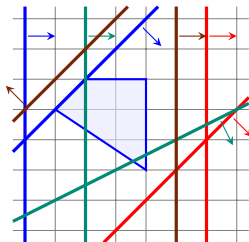
Given two disjuncts  $A$  and  $B$

For each affine constraint  $t(\mathbf{x}) \geq 0$  of  $A$ , determine its effect on  $B$

- $\min t(\mathbf{x}) > -1$  over  $B$   
 $\Rightarrow$  **valid** constraint
- $\max t(\mathbf{x}) < 0$  over  $B$   
 $\Rightarrow$  **separating** constraint

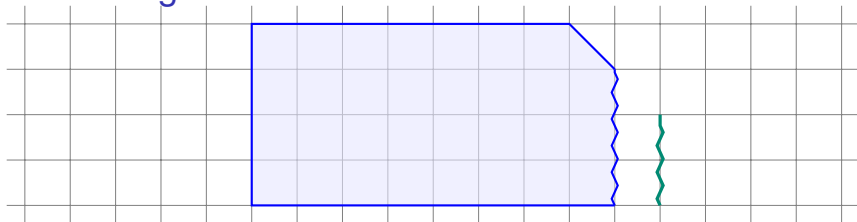
special cases:

- ▶  $t = -u - 1$  with  $u(\mathbf{x}) \geq 0$  a constraints of  $B$   
 $\Rightarrow$  constraint is **adjacent to an inequality** of  $B$
  - ▶  $t(\mathbf{x}) = -1$  over  $B$   
 $\Rightarrow$  constraint is **adjacent to an equality** of  $B$
- otherwise (attains both positive and negative values over  $B$ )  
 $\Rightarrow$  **cut** constraint



Note: affine expression  $t(\mathbf{x}) \geq 0$  has integer coefficients  
 min and max computed using (incremental) LP solver

# Coalescing Cases

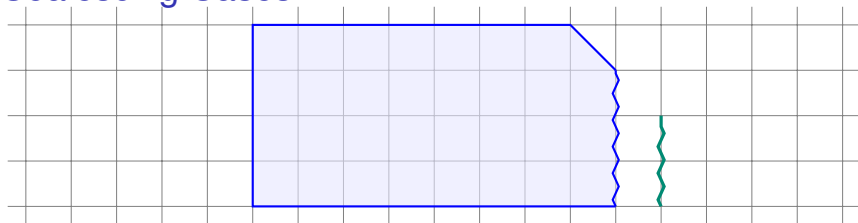


Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
- cut: otherwise



# Coalescing Cases

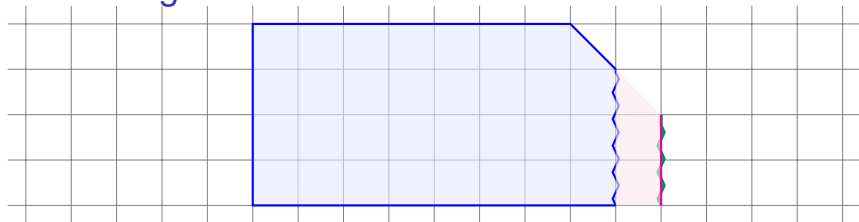


- ⑤ **A** has single inequality adjacent to equality of **B** (other constraints of **A** are valid)

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  
 $t = -u - 1$
  - adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑤  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

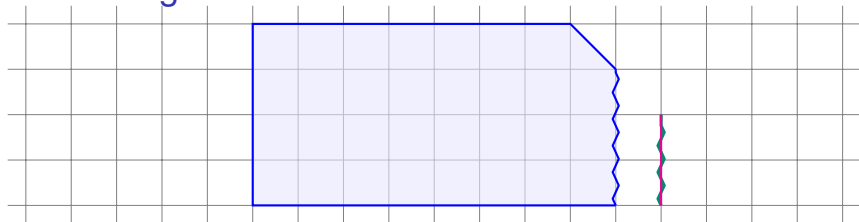
Result of replacing  $t(\mathbf{x}) \geq 0$  by  $t(\mathbf{x}) \leq -1$  is a subset of  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑤  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

Result of replacing  $t(\mathbf{x}) \geq 0$  by

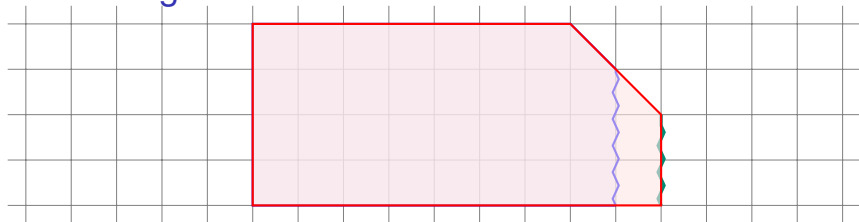
$t(\mathbf{x}) \leq -1$  is a subset of  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑤  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

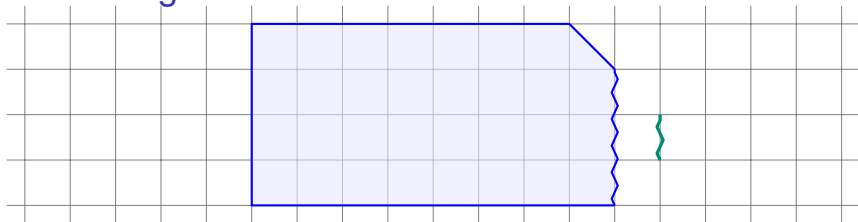
Result of replacing  $t(\mathbf{x}) \geq 0$  by  $t(\mathbf{x}) \leq -1$  is a subset of  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

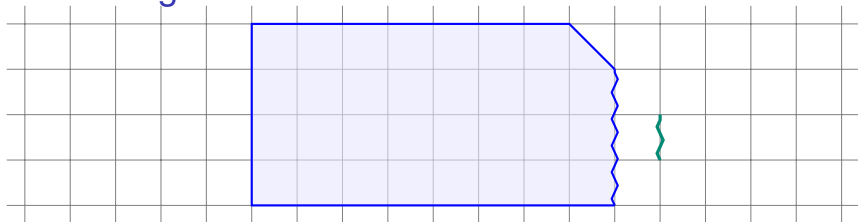
# Coalescing Cases



Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  
 $t = -u - 1$
  - adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑥  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

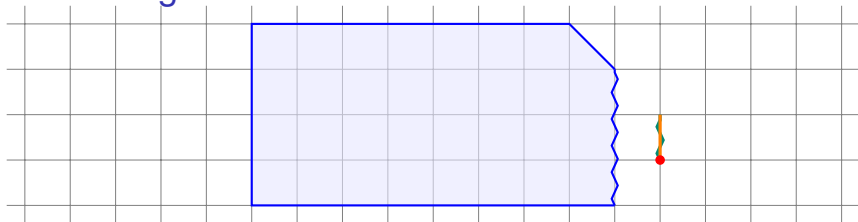
Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑥  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

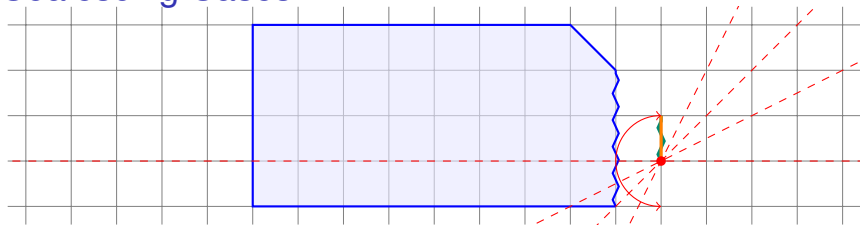
Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑥  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

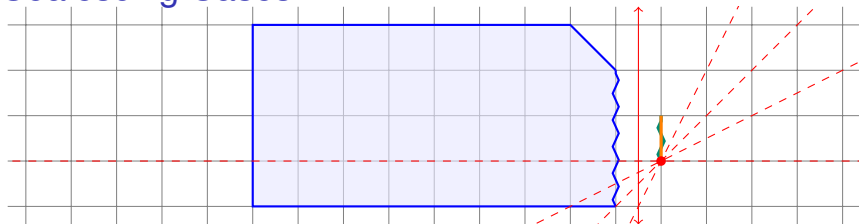
⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise



# Coalescing Cases



- ⑥  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

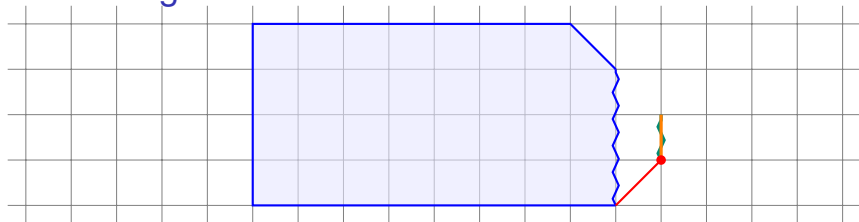
Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑥  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

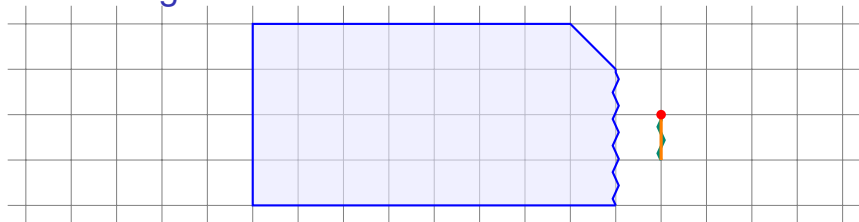
Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  $t = -u - 1$
  - ▶ adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑥  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

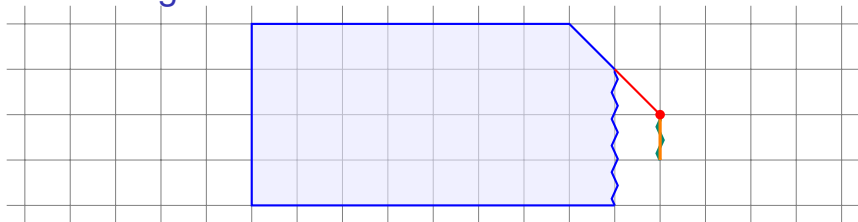
Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  $t = -u - 1$
  - ▶ adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑥  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

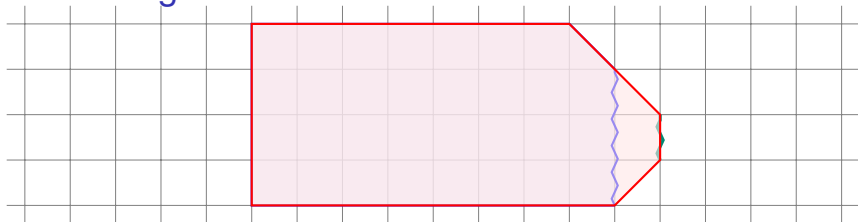
Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑥  $A$  has single inequality adjacent to equality of  $B$  (other constraints of  $A$  are valid)

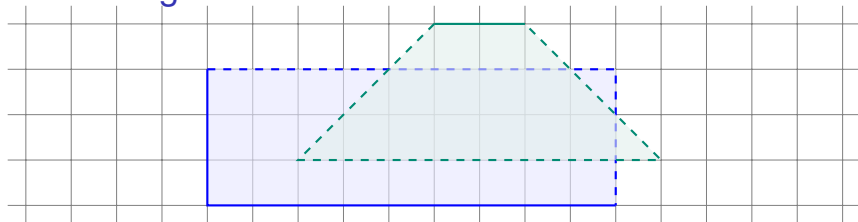
Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

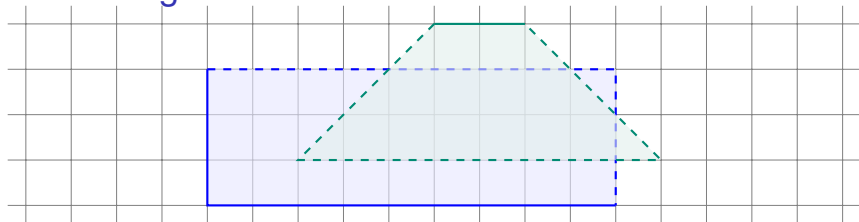
# Coalescing Cases



Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



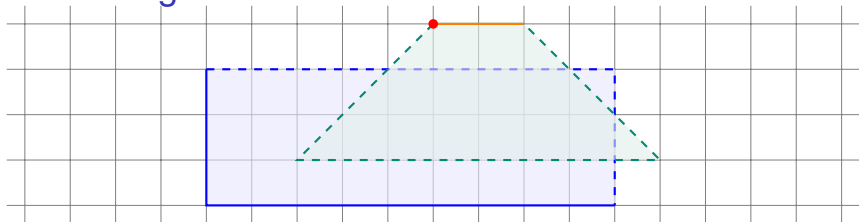
- ⑦  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints  
(check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑦  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

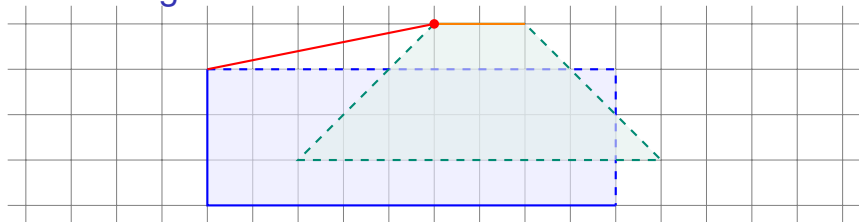
⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints (check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  $t = -u - 1$
  - ▶ adjacent to equality:  $t = -1$
- cut: otherwise



# Coalescing Cases



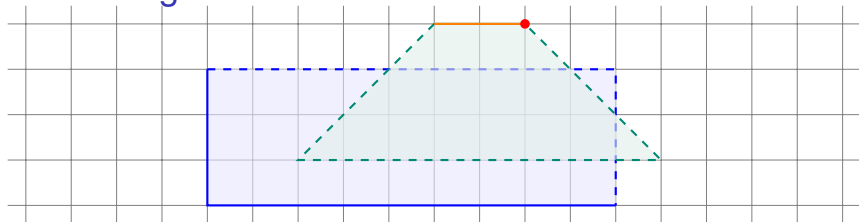
- 7  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints (check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  $t = -u - 1$
  - ▶ adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



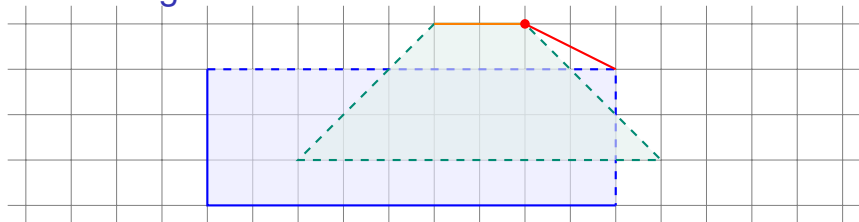
- ⑦  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints  
(check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



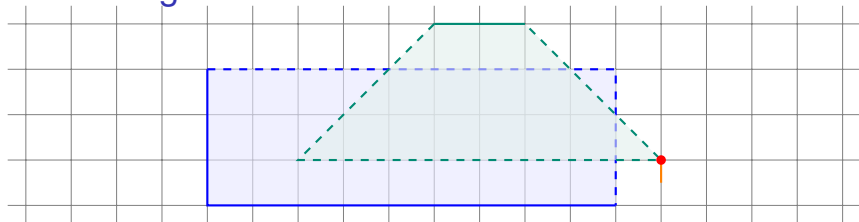
- 7  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints  
(check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



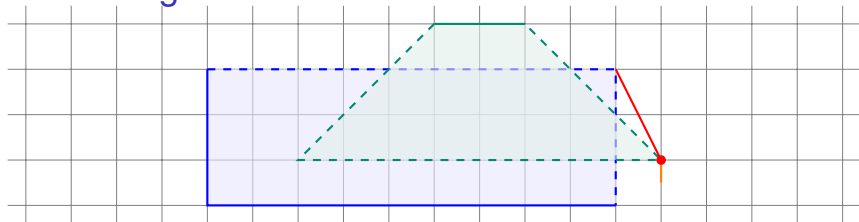
- ⑦  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints (check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  $t = -u - 1$
  - ▶ adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



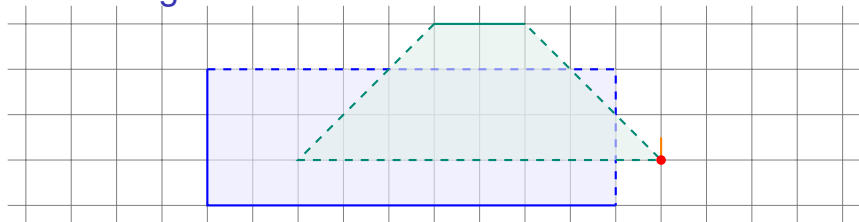
- ⑦  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints (check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  $t = -u - 1$
  - ▶ adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



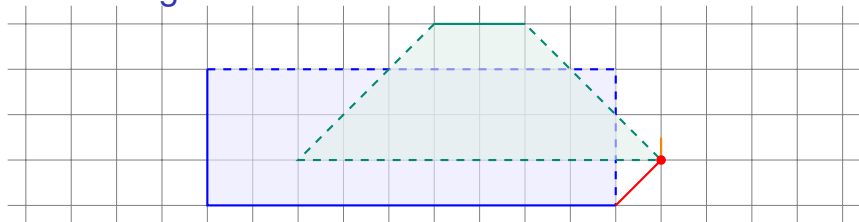
- ⑦  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints  
(check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑦  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints  
(check final number of constraints does not increase)

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



- 7  $B$  extends beyond  $A$  by at most one and all cut constraints of  $B$  can be wrapped around shifted facet of  $A$  to include  $A$

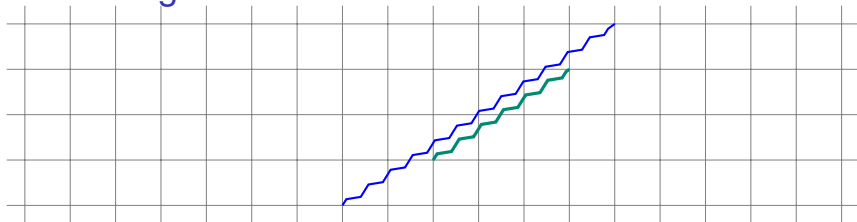
⇒ replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints  
(check final number of constraints does not increase)

## Constraint $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise



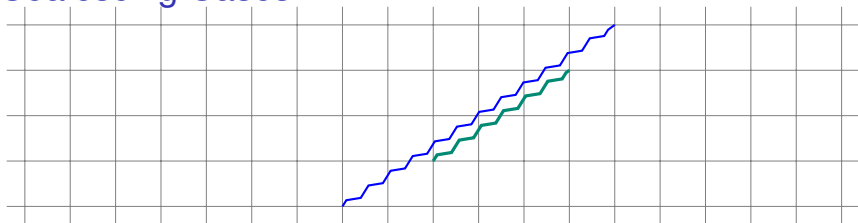
# Coalescing Cases



Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - ▶ adjacent to inequality:  
 $t = -u - 1$
  - ▶ adjacent to equality:  
 $t = -1$
- cut: otherwise

# Coalescing Cases



- 8  $A$  has equality adjacent to equality of  $B$

Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

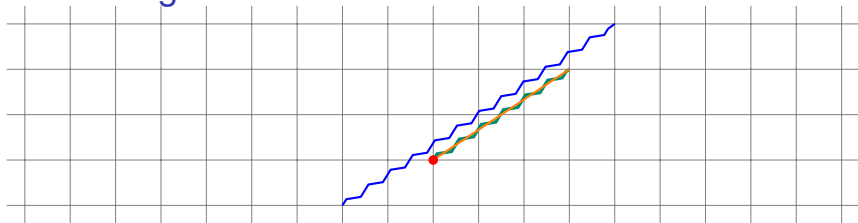
Non-valid constraints of  $A$  (except  $t(\mathbf{x}) \geq 0$ ) can be wrapped around  $t(\mathbf{x}) \leq 0$  to include  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- 8  $A$  has equality adjacent to equality of  $B$

Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

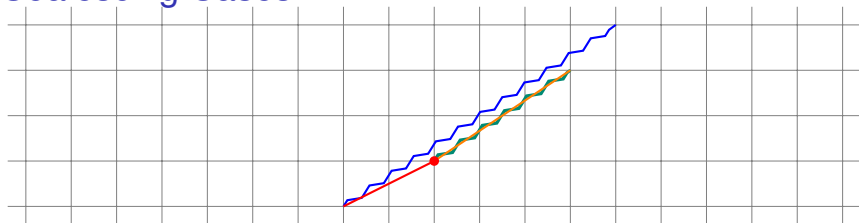
Non-valid constraints of  $A$  (except  $t(\mathbf{x}) \geq 0$ ) can be wrapped around  $t(\mathbf{x}) \leq 0$  to include  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑧  $A$  has equality adjacent to equality of  $B$

Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

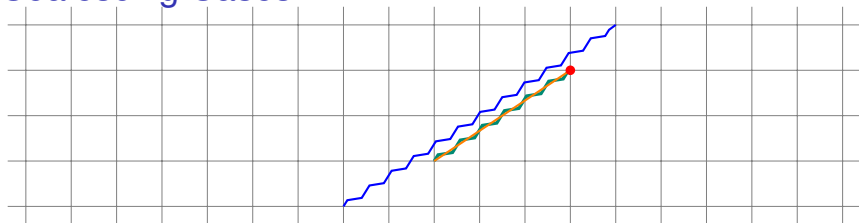
Non-valid constraints of  $A$  (except  $t(\mathbf{x}) \geq 0$ ) can be wrapped around  $t(\mathbf{x}) \leq 0$  to include  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- 8  $A$  has equality adjacent to equality of  $B$

Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

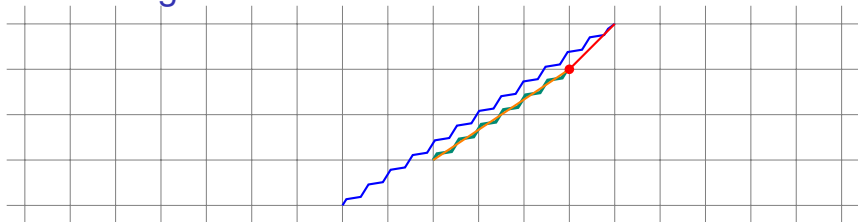
Non-valid constraints of  $A$  (except  $t(\mathbf{x}) \geq 0$ ) can be wrapped around  $t(\mathbf{x}) \leq 0$  to include  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- 8  $A$  has equality adjacent to equality of  $B$

Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

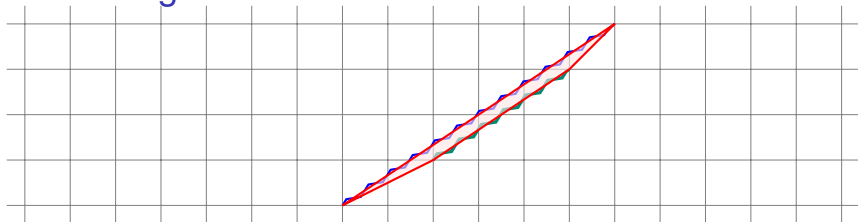
Non-valid constraints of  $A$  (except  $t(\mathbf{x}) \geq 0$ ) can be wrapped around  $t(\mathbf{x}) \leq 0$  to include  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Coalescing Cases



- ⑧  $A$  has equality adjacent to equality of  $B$

Non-valid constraints of  $B$  (except  $t(\mathbf{x}) \leq -1$ ) can be wrapped around  $t(\mathbf{x}) \geq -1$  to include  $A$

Non-valid constraints of  $A$  (except  $t(\mathbf{x}) \geq 0$ ) can be wrapped around  $t(\mathbf{x}) \leq 0$  to include  $B$

$\Rightarrow$  replace  $A \cup B$  by set bounded by all valid constraints and all wrapped constraints

Constraint  $t(\mathbf{x}) \geq 0$

- valid:  $\min t(\mathbf{x}) > -1$
- separate:  $\max t(\mathbf{x}) < 0$ 
  - adjacent to inequality:  $t = -u - 1$
  - adjacent to equality:  $t = -1$
- cut: otherwise

# Existentially Quantified Variables and Equalities

- Quantifier elimination in isl replaces existentially quantified variables by integer divisions of affine expressions in other variables
- These integer divisions are sorted prior to coalescing
- $A$  and  $B$  have same number of integer divisions/existentials  
⇒ try all cases
- integer divisions of  $A$  form subset of those of  $B$   
(after exploiting equalities of  $B$ )  
⇒ check if  $B$  is a subset of  $A$
- integer divisions of  $B$  form subset of those of  $A$  and equalities of  $B$  simplify away the integer divisions of  $A$  not in  $B$   
⇒ introduce integer divisions in  $B$  and try all cases



# Outline

## 1 Introduction and Motivation

- Polyhedral Compilation
- The need for coalescing
- Traditional “Coalescing”

## 2 Coalescing in `isl`

- Rational Cases
- Constraints adjacent to inequality
- Constraints adjacent to equality
- Wrapping
- Existentially Quantified Variables

## 3 Conclusions

# Conclusions

- it is important to keep the number of disjuncts in a set representation as low as (reasonably) possible
- coalescing in `isl`
  - ▶ never increases the total number of constraints
  - ▶ based on solving LP problems with same dimension as the original set
  - ▶ recognizes a set of patterns